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Title word cross-reference

19 [FSHR⁺21].

2014 [SPGB21].

ability [YZL⁺16]. **Acceptability**
[GAG⁺21]. **Acceptance** [MTCKS21].
achieve [HM13]. **ACM**
[JS18, JS19, SJ18, SJ22]. **Acquisition**
[FSLN19, LMD14]. **ACT** [THH⁺13].
ACT-R [THH⁺13]. **ACT-R/E** [THH⁺13].
Action [WE20]. **Activation** [BBM⁺21].
active [FSP15]. **Activities** [MNM18].
activity [CBO⁺16, JBF⁺14]. **acts** [BWS17].

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[Vel18]. **Aid** [MNM18]. **aided** [Tan15]. **Aids**
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Alzheimer [PPRR20]. **analog** [PSB⁺16].
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Android [Har16, KTTO13]. **animal**
[PSB⁺16]. **Animation** [STH19].
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Daily [MNM18]. **dangerous** [Har16]. **Data** [DKI19, DBK21, GCSY16]. **Data-Driven** [DBK21]. **Dead** [Fis21]. **Decision** [CNS⁺20]. **Deep** [MLF⁺21]. **Delivered** [GAG⁺21]. **Dementia** [GHD21]. **demonstration** [SD15]. **Dependent** [DWM22]. **Depression** [BBM⁺21]. **Descriptions** [WSG⁺22]. **Design** [AORK22, CBK⁺18, MPCV13, MHV⁺21, MD21, OH22, Aug14, DSPM15, FLA⁺13, HF14, JBF⁺14, MBK⁺12, PSB⁺16, RFLM13, WML15]. **Designing** [HJ14, HLWV14, KLE19, SRK14, WRPZ21, WTDS20, JBF⁺14, WS13]. **Designs** [MBZA20]. **Destruction** [LSB⁺20]. **determinism** [HLWV14]. **Development** [LMD14, PB18]. **Diagnostic** [HHHA19]. **dialog** [DTT⁺13]. **dialogue** [MBLD17]. **dialogue** [SA15]. **Dialogues** [SSK⁺19]. **Did** [DLG⁺19, SRHE21]. **Difference** [CCL⁺19]. **Different** [ZZKC19]. **Dig** [BFL⁺17]. **Dimensions** [Oka18]. **direct** [GCMC15]. **Directions** [LLT21]. **Disclosure** [NKT20]. **Disease** [PPRR20, WTDS20]. **dishonest** [Har16]. **Disorder** [JBJ⁺20]. **dissonance** [LHP⁺13]. **Distance** [FSM12]. **Distance-based** [FSM12]. **distributed** [RC15]. **Diverse** [SJ19b, MBLD17]. **Do** [JL19, PES20]. **does** [JL16]. **Dominance** [LCM⁺19]. **don't** [Asa16]. **drama** [SCG17]. **Driven** [DBK21]. **driver** [NWS15]. **Drone** [ZZKC19]. **drones** [WM16]. **During** [JW21, FDC⁺22, MPCV13, MU15]. **Dynamic** [LNG22, MBK⁺12]. **dynamic-autonomy** [MBK⁺12]. **Dynamically** [WSG⁺22]. **Dynamics** [JDS⁺21, CT13].

Ease [CCL⁺19]. **Editorial** [AJS19, JS17, JS19, SJ19a, SJ19b]. **Editors** [SJ18]. **Editors-in-Chief** [SJ18]. **Education** [SBB17, MBLD17, ZCV⁺17]. **EEG** [MHI16]. **EEG-based** [MHI16]. **Effect** [Fis21, KF18, LRS18]. **Effective** [MBZA20]. **Effectiveness** [WSG⁺22]. **Effects** [BSC18, vSPKB20, MHI16, Sch14, YZL⁺16]. **Efficacy** [PB18]. **Effort** [FDC⁺22]. **Effortful** [VPR⁺22]. **Egocentric** [KDC⁺21]. **Elderly** [NKT20, FM13, MBK⁺12]. **Embodied** [WTC⁺21, THH⁺13]. **Embodiment** [NACB20]. **emergency** [ITI15]. **Emerging**

[LLT21]. **Emotional** [LSB⁺20, PT20]. **Empathic** [AOSM⁺19, OP14]. **Enabling** [BWS17, CXJS13, DSPM15, GSF⁺13, HM13]. **Encouraging** [NKT20]. **endpoint** [MU15]. **Engage** [MLF⁺21, SHSK20, CBO⁺16]. **engagement** [RFLM13]. **Engaging** [SOCAG⁺19]. **engineering** [Sch14]. **Enhancement** [ZFS⁺20]. **Enhancements** [FSP15]. **enhancing** [Tan15]. **environment** [BDO⁺13, WS13]. **environment-based** [WS13]. **Errors** [TO21, WAAR20]. **Ethnography** [CK20]. **Evaluating** [JW21, BTLY15]. **Evaluation** [GAG⁺21, RPB21, VK19, ZFS⁺20, BDO⁺13, RFLM13, SRK14]. **Event** [Gär19]. **evocative** [LZ17]. **Exceptions** [SAS19]. **exchange** [HS15]. **exchanges** [PJ17]. **Execution** [BA18]. **exercise** [FM13]. **Exoskeleton** [JL19]. **Experience** [KF18]. **Experiences** [JBJ⁺20, NKT20]. **experimental** [KSNL13]. **Experiments** [Fis21, HZ21, SVD21, TM12]. **Explain** [HPY21, SHSK20]. **Explainability** [TZ21]. **Explainable** [DDMZ21, WTC⁺21]. **Explaining** [AKS21, WDR⁺20]. **Explanation** [AKS21, HGA⁺21]. **Explanations** [HPY21]. **Exploration** [JS21, GCSY16]. **Exploratory** [RKD⁺21]. **Exploring** [SAS19]. **exposing** [You17]. **Expressing** [LBA⁺21]. **Expressions** [PT20]. **Expressive** [SOCAG⁺19, VK19, WRPZ21]. **eye** [AS17].

Facial [PT20]. **Facilitate** [JBJ⁺20, RPB21]. **Facilitating** [CCT⁺18, FSM12]. **facility** [MN13]. **Fascinating** [Vel18]. **Features** [KF21]. **Feedback** [CCT⁺18, BTLY15]. **feel** [JL16]. **Fiction** [MWJO19]. **Field** [AOSM⁺19, BFW⁺20, MLF⁺21, TM12, TOW⁺13]. **Findings** [RKD⁺21]. **floor** [CT13]. **Foe** [MTCKS21]. **foraging** [KSNL13]. **force** [Asa16, HS15, RFL⁺15]. **Forceful** [FDC⁺22]. **forestry** [WS13]. **Formation** [vSPKB20]. **fostering** [PSB⁺16]. **Foundation** [HGA⁺21, SJ19b]. **Framework** [ASJD19, AORK22, JBJ⁺20, BFR14, TKC14]. **Frameworks** [Mil13]. **Framing** [WAAR20]. **Free** [BA18, ZCW⁺16]. **Friend** [MTCKS21]. **Fully** [GPFA20, WTDS20]. **Functional** [CS13]. **Functionality** [WAAR20]. **Future** [Dau18, SJ19b, PSB⁺16, WS13].

G [SVD21]. **Game** [MD21]. **Games** [GAG⁺21, MD21, SA15]. **gap** [KPSS12]. **gaps** [SPGB21]. **Gaze** [SH21, AS17]. **GEDIS** [ZFS⁺20]. **GEDIS-UAV** [ZFS⁺20]. **General** [CBK⁺18, dSCV⁺13]. **General-Purpose** [CBK⁺18, dSCV⁺13]. **Generate** [Gär19]. **Generating** [KF21]. **Generation** [HGA⁺21, VK19, Tan15]. **German** [KAG21]. **Gesture** [CCT⁺18, KTTO13]. **gesture-centric** [KTTO13]. **Gestures** [MHV⁺21, MPCV13, ZCW⁺16]. **Glanceable** [KF21]. **Global** [BA18]. **globe** [GE13]. **goals** [HM13]. **Going** [PES20]. **graduate** [You17]. **Granular** [JS21]. **ground** [BTLY15, WML15]. **ground-based** [BTLY15]. **Groundwork** [GPFA20]. **Group** [AOSM⁺19, WE20]. **Groups** [JDS⁺21, TCR20]. **Guided** [FGT18]. **guidelines** [Rie12].

Hacking [HB18]. **hand** [Tan15, ZCW⁺16]. **Handcrafted** [SH19]. **handovers** [SLD⁺13]. **handrest** [FSP15]. **Hands** [Asa16]. **Happens** [JW21]. **Happy** [Bro18]. **Haptic** [CCT⁺18, NWS15, Oka18, SFEK15, BTLY15, ITI15, RC15, SD15]. **haptics** [MF15]. **helicopter** [DSPM15]. **Hesitation** [MHV⁺21, MPCV13]. **historical** [OP14]. **Hoffman** [SVD21, Fis21]. **Home** [BBM⁺21, WRPZ21, MBK⁺12]. **homes** [TOW⁺13]. **Households** [BFW⁺20]. **HRI** [BFL⁺17, PB18, AJS19, Asa16, ASJD19, Bro18, Fis21, GE13, Goo13, KB13, KPSS12, KA13, MF15, MBZA20, Mat18, MBLD17,

NMW⁺²¹, Rie12, RFLM13, SBB17, SJ19b, SAS19, SVD21, WAAR20, You17, ZCV⁺¹⁷].

Human

[BSC18, CCT⁺¹⁸, CNS⁺²⁰, CRA21, DC16, Dau18, DKI19, FSHR⁺²¹, FDC⁺²², Fis22, FGT18, HCR18, HHHA19, HZ21, HF14, HB18, JA20, JW21, JH18, KG18, KSNL13, KF18, LBA⁺²¹, LNG22, LO20, LSB⁺²⁰, MF15, MTCKS21, ME20, MHV⁺²¹, NKFS18, ORPW19, Oka18, OH22, PT20, PSB⁺¹⁶, PB18, RPB21, SJ18, SJ22, STH19, SVD21, SSK⁺¹⁹, TCR20, TO21, Vel18, WSG⁺²², vSPKB20, AS17, BFR14, BFL⁺¹⁷, BDO⁺¹³, BTLY15, BGJK16, CS13, CXJS13, DTT⁺¹³, GSF⁺¹³, GCMC15, HBAZ15, HMGC13, HS15, KTTO13, LMD14, LHP⁺¹³, MHI16, MPCV13, MU15, PJ17, dSCV⁺¹³, SA15, SLD⁺¹³, TGS12, Tan15, TKC14, THH⁺¹³, Wag15, WBS15, vdBBD⁺¹⁶].

Human-animal [PSB⁺¹⁶].

Human-Collective [CRA21].

Human-Guided [FGT18].

Human-Human [ORPW19].

Human-Mobile [CCT⁺¹⁸].

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[DSL13, TOW⁺¹³]. **Intent** [JA20, LBA⁺²¹].

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[Dau18, FSHR⁺²¹, Fis22, FDN20, HCR18, HZ21, JH18, KKC⁺²², KLE19, KG18, KF18,

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WSG⁺²², AS17, BFR14, BBR⁺¹³, BFL⁺¹⁷, BDO⁺¹³, BTLY15, BGJK16, CS13, CXJS13,

CBO⁺¹⁶, FSM12, FLA⁺¹³, GSF⁺¹³, HM13, KSNL13, KTTO13, LMD14, LHP⁺¹³,

MBK⁺¹², MU15, OP14, RFL⁺¹⁵, dSCV⁺¹³, TKC14, THH⁺¹³, Wag15, WS13, WBS15,

vdBBD⁺¹⁶, DC16, HF14, MF15, SJ18, SJ22]. **Interactions**

[LO20, ORPW19, SVD21, BWS17, CT12,

HMGC13, SFEK15, SDFSM17]. **Interactive** [AKS21, MLF⁺²¹, MD21, SCG17, VPR⁺²²,

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[TGS12]. **Intersections** [NACB20]. **Intra**

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GE13, Goo13, HCR18, HF14, JS19, KB13, MF15, MAC15, SBB17, TGS12, JS17].

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Journal [SJ22, DC16, HF14, MF15].

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DKI19, DBK21, FSLN19, KF18, LO20,
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SHSK20, SD15, WDR⁺20, BFL⁺17, TM12].
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[HPY21]. **likeness** [MHI16]. **Limb**
[GPFA20]. **Linguistic** [FSLN19].
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[Aug14, MNM18]. **Locomotion** [LCM⁺19].
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makes [Sch14]. **Making**
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[SRK14, TKC14]. **manipulability**
[SFEK15]. **manipulation** [MBK⁺12].
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[FDN20, MBZA20]. **Measuring**
[BLCW⁺20]. **mechanical** [LJR17, OP14].
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[DWM22]. **Meta-analysis** [DWM22].
metamorphosis [OP14]. **Method**
[JDS⁺21, HLWV14]. **methodology** [Tan15].
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VK19, BDO⁺13, WS13]. **Metrics**
[MBZA20]. **Mind** [SS18, HJ14]. **Minimize**
[FDC⁺22]. **Minority** [SSQS21]. **Mixed**
[CHS21, DLDS⁺15, SVD21].
Mixed-initiative [CHS21, DLDS⁺15].
Mobile
[BFW⁺20, CCT⁺18, CHS21, RKD⁺21,
SPGB21, Vel18, BTLY15, RFL⁺15].
Mobility [JL19, SD15]. **modal** [IOLB22].
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MKH14, MU15, Tan15]. **Modeling**
[SSK⁺19]. **Models**
[PES20, RKD⁺21, FSM12]. **Modified**
[ZFS⁺20]. **Monitoring** [ME20].
Morphology [KLE19]. **Motion**
[BA18, KF21, RPB21, SOCAG⁺19, MHI16].
Motions [VK19]. **Motor** [FDN20].
movement [HJ14, Tan15]. **Movie** [Sch14].
Moving [WRPZ21]. **mu** [MHI16]. **Multi**
[IOLB22, CBO⁺16, KTTO13, RC15,
SFEK15]. **multi-activity** [CBO⁺16].
Multi-modal [IOLB22]. **multi-party**
[KTTO13]. **multi-robot** [SFEK15].
multi-user [RC15]. **multidisciplinary**
[BFL⁺17]. **Multilevel** [ASJD19].
Multimodal
[BBR⁺13, KLE19, ZCG⁺20, CT12, LMD14].
Multiparty [SSK⁺19]. **Multiplayer**
[MD21]. **Muscular** [FDC⁺22]. **Museum**
[MLF⁺21].

Natural [FLA⁺13, GPFA20]. **near** [CS13].
near-infrared [CS13]. **Need**
[HPY21, GCSY16]. **needs** [MM16].
Negation [FSLN19]. **Negative** [CCL⁺19].
Negotiation [MHV⁺21]. **nets** [CT12].
network [DKI19, GSF⁺13, PCB⁺17].
networked [RC15]. **Neural** [DKI19].
Neural-network-based [DKI19]. **Next**

[FSHR⁺21]. **No** [FSLN19]. **non** [DLDS⁺15, SCG17]. **non-pilots** [DLDS⁺15]. **non-technical** [SCG17]. **Nonanthropomorphic** [LCM⁺19]. **Nonverbal** [MHV⁺21]. **Norm** [SAS19]. **Normative** [SSQS21]. **Number** [WE20].

obedience [GCSY16]. **Object** [FGT18, HS15]. **Objective** [ME20]. **objects** [LZ17]. **off** [RPB21]. **Older** [BFW⁺20, GAG⁺21, JL19, PPRR20, MN13]. **One** [SSQS21]. **online** [HS15]. **Ontology** [ORPW19]. **Open** [IOLB22, SSK⁺19, SH19, CXJS13]. **Open-Source** [SH19]. **Open-World** [SSK⁺19]. **Operated** [CHS21]. **operation** [NWS15]. **Operator** [ZZKC19, MU15]. **Opportunity** [Vel18]. **Our** [SJ19b]. **overlap** [Sch14]. **overview** [OP14]. **Oz** [Rie12].

Paediatric [CBK⁺18]. **paired** [SD15]. **paradigm** [KA13]. **parametrized** [CT13]. **Parkinson** [WTDS20]. **Participatory** [AORK22]. **Partner** [VPR⁺22]. **parts** [LJR17]. **party** [KTTO13]. **Past** [Dau18]. **Patient** [Fis21]. **pedestrian** [ITI15]. **peer** [HBAZ15]. **peer-based** [HBAZ15]. **People** [HPY21, JLV⁺21, SRHE21, WTDS20, BRSTV17, MBK⁺12, MM16, Wag15]. **Perceived** [BLCW⁺20, CCL⁺19, WAAR20, MHI16, YZL⁺16]. **Perception** [JS21, PT20, SRHE21, TCR20, WE20, vSPKB20]. **perceptions** [WBS15]. **Perceptual** [TZ21]. **Performance** [JW21, HBAZ15, vdBBD⁺16]. **Periodically** [DBK21]. **Personality** [NKT20, WRPZ21]. **Personalization** [LRS18]. **Personalizing** [MNM18]. **Personas** [WRPZ21]. **Persons** [GHD21]. **perspective** [KA13, PJ17]. **perspectives** [GE13]. **Petri** [CT12]. **Phase** [SST21]. **Physical** [LO20, ME20, GCMC15, MU15, PCB⁺17]. **Physically** [CTA21]. **Physiological** [ZCG⁺20]. **physiologically** [LJR17]. **pilots** [DLDS⁺15]. **planar** [FSP15]. **Planned** [PES20]. **Planning** [BA18, CNS⁺20, FDC⁺22, NKFS18]. **Plant** [BBM⁺21]. **platform** [LMD14]. **Please** [GCSY16]. **police** [Asa16]. **Policies** [ORPW19]. **policy** [DC16]. **poor** [vdBBD⁺16]. **position** [RC15]. **Power** [TRK21]. **Practice** [Mat18]. **Pre** [KF21]. **Pre-attentive** [KF21]. **Predictability** [SRHE21]. **Prediction** [ZCG⁺20, MU15]. **Preferences** [CTA21, KAG21]. **Preliminary** [JBJ⁺20, RFLM13]. **Presence** [MWJO19, NACB20]. **Primer** [Fis21, HZ21, SVD21]. **Principles** [KKC⁺22]. **privacy** [WM16]. **Private** [BFW⁺20]. **Probabilistic** [JA20]. **Problem** [TZ21, BFL⁺17]. **Process** [JS18]. **Processed** [WSG⁺22]. **Processing** [KF21]. **Product** [DBK21]. **Proficiencies** [LNG22]. **Profit** [FNJB20]. **progress** [MBLD17]. **Prohibition** [FSLN19]. **projects** [GE13]. **Promote** [LR18, MBLD17, TM12]. **prototype** [SRK14]. **proxemic** [MM16]. **Proximate** [WAAR20]. **Psychological** [vSPKB20]. **Public** [MLF⁺21, SPGB21, BDO⁺13, GSF⁺13]. **Punish** [JW21]. **Punishment** [JW21]. **Purpose** [CBK⁺18, dSCV⁺13]. **push** [GCMC15].

Quality [FDN20].

R/E [THH⁺13]. **R2D2** [KLE19]. **Rack** [RKD⁺21]. **RALL** [Ran20]. **reactions** [LHP⁺13]. **Reactive** [BA18]. **Real** [LO20, BFL⁺17]. **Real-Time** [LO20]. **real-world** [BFL⁺17]. **Reasoning** [WDR⁺20]. **receive** [DSPM15]. **receiving** [TM12]. **Recognition** [JA20, NMW⁺21]. **reconnaissance** [WML15]. **reduce** [HLWV14]. **redundant** [WEG⁺13]. **Reflecting** [MWJO19]. **reformulation** [MBLD17]. **Reframing** [LR18, MBLD17].

regulating [Har16]. **regulation** [CT13]. **Rehabilitation** [CBK⁺18, LLT21, Tan15]. **Reinforcement** [KF18, MLF⁺21]. **Rejective** [FSLN19]. **related** [Tan15]. **Relationship** [vSPKB20]. **relationships** [Mil13]. **Release** [LSB⁺20]. **Relevance** [Mat18]. **Reliability** [WAAR20]. **Reminders** [BBM⁺21]. **remote** [DSPM15, MBK⁺12]. **Remotely** [CHS21]. **repertoire** [HM13]. **reporting** [Rie12]. **Representation** [AJS19, RFL⁺15]. **Representations** [Gär19]. **Research** [FSHR⁺21, KPSS12, YZL⁺16]. **resource** [MPCV13]. **Results** [BFW⁺20, TOW⁺13]. **resupply** [DSPM15]. **Review** [GHD21, JS18, STH19, WTC⁺21, AS17, Rie12, ZCV⁺17]. **Reviewer** [FS17]. **Reviewing** [FS17]. **rhythm** [MHI16]. **rise** [LZ17]. **roadable** [DLDS⁺15]. **Robo** [MD21]. **Robot** [AOSM⁺19, AORK22, BFW⁺20, BSC18, BBM⁺21, CBK⁺18, CCT⁺18, CNS⁺20, CK20, DC16, Dau18, DLG⁺19, DK19, DBK21, FSHR⁺21, FDC⁺22, Fis22, Gär19, GAG⁺21, HGA⁺21, HPY21, HCR18, HHHA19, HZ21, HF14, JW21, JH18, JDS⁺21, KKC⁺22, KLE19, KG18, KF21, LBA⁺21, LRS18, LCM⁺19, LNG22, LO20, LSB⁺20, MF15, MTCKS21, ME20, MHV⁺21, MNM18, NKFS18, NKT20, Oka18, OH22, PT20, PPRR20, PB18, RPB21, SJ18, SJ22, SST21, SRHE21, STH19, SH21, SH19, Tan15, TCR20, TO21, Vel18, VK19, VPR⁺22, WSG⁺22, WAAR20, WDR⁺20, WTDS20, WE20, ZCG⁺20, vSPKB20, AS17, BRSTV17, BFR14, BBR⁺13, BFL⁺17, BDO⁺13, BTLY15, CS13, CXJS13, CBO⁺16, DTT⁺13, DSMS17, FM13, FSM12, FLA⁺13, GSF⁺13, GCMC15, HBAZ15, HMG13, HS15, HM13, KA13, KTTO13, LMD14, LHP⁺13, LJR17, MHI16]. **robot** [MN13, MM16, MPCV13, MKH14, MU15, PSB⁺16, PJ17, RFL⁺15, dSCV⁺13, SRK14, Sch14, SVD21, SFEK15, SA15, SLD⁺13, TM12, TKC14, THH⁺13, Wag15, WBS15, YZL⁺16, vdBBD⁺16, Ran20]. **Robot-AI** [Vel18]. **Robot-aided** [Tan15]. **Robot-Assisted** [JDS⁺21, ZCG⁺20, Ran20]. **Robot-Centric** [TCR20]. **Robot-Delivered** [GAG⁺21]. **Robot-Initiated** [JW21]. **Robot-Interaction** [PB18]. **Robot-specific** [KLE19]. **robot-to-human** [PJ17]. **Robotic** [AKS21, DDMZ21, GPFA20, JBJ⁺20, JS21, KDC⁺21, SOCAG⁺19, OP14]. **Robotics** [CTA21, CK20, HB18, JA20, TZ21, YZL⁺16, ZCV⁺17]. **Robots** [BLCW⁺20, CCL⁺19, CHS21, FNJB20, FSLN19, GHD21, JW21, JLV⁺21, JH18, KAG21, LLT21, LR18, MM16, MWJO19, MD21, SSQS21, SPGB21, SS18, SHSK20, Vel18, Wag15, WRPZ21, Aug14, BWS17, BTLY15, GCSY16, Har16, HJ14, HM13, HLWV14, MBK⁺12, SRK14, SCG17, Sch14, SDFSM17, TOW⁺13, WML15, WEG⁺13]. **Robots-from** [SS18]. **Robust** [JH18]. **Role** [SAS19, HLWV14]. **Roles** [LLT21, HLWV14]. **Roomba** [JL16]. **Routes** [PES20]. **Safety** [SPGB21]. **Say** [FSLN19]. **Scaffold** [SHSK20]. **Scalable** [FDN20]. **Scale** [PB18]. **Scales** [ASJD19]. **Scenarios** [NMW⁺21]. **Scholarship** [SJ19b]. **Science** [KG18, MWJO19]. **sciences** [TGS12]. **scientific** [MBLD17]. **SE** [PB18]. **SE-HRI** [PB18]. **seamless** [SLD⁺13]. **Second** [SHSK20]. **Second-language** [SHSK20]. **See** [SRHE21]. **Selection** [CRA21]. **Self** [NKT20, PB18]. **Self-Disclosure** [NKT20]. **Self-Efficacy** [PB18]. **Semantics** [Gär19]. **Sensory** [JBJ⁺20]. **Service** [BFW⁺20, Vel18]. **Serving** [SPGB21]. **Shaping** [SJ19b]. **Shared** [JA20, LBA⁺21, MAC15, NWS15, SA15, SD15]. **Shoe** [RKD⁺21]. **shoot** [Asa16]. **Shopkeeper** [DLG⁺19, DBK21]. **Should** [JLV⁺21, BRSTV17]. **side** [MKH14].

side-by-side [MKH14]. **signal** [MM16].
Signals [ZCG⁺20, vdBBD⁺16]. **Situ**
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 HM13, MM16, dSCV⁺13, Sch14, You17].
Socially [MNM18, MD21, WTDS20, FM13,
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spectroscopy [CS13]. **Spectrum** [JBJ⁺20].
speculative [Aug14]. **Speech**
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Strategies [RPB21, ZZKC19]. **students**
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subjects [SCG17]. **Successful** [LR18].
Supervisory [HHHA19, Mil13]. **support**
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suppression [MHI16]. **Surgery**
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 [PCB⁺17]. **Survey** [Ran20, VK19].
sustainability [JS17]. **Swarm**
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Systematic [GHD21, STH19, Rie12].
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 [FGT18, JW21, LNG22, VPR⁺22, BWS17,
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testing [LMD14]. **Their**
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THRI [JS18, JS19]. **Time**
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 [ZZKC19]. **Traits** [NKT20]. **Trajectory**
 [KF21, LO20, Tan15]. **Transactions**
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Transparency [vSPKB20]. **Trees**

[HGA⁺21]. **Trials** [BFW⁺20, TOW⁺13]. **Trust** [CNS⁺20, OH22, WAAR20, DSMS17, PSB⁺16]. **Trust-Aware** [CNS⁺20]. **trustworthy** [ITI15]. **tu** [Har16]. **turn** [CT12]. **turn-taking** [CT12]. **Tutoring** [LRS18]. **Two** [BGJK16, BRSTV17, KSNL13, ZCV⁺17]. **types** [KSNL13].

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X [SVD21].

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