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ability [YZL⁺16]. **achieve** [HM13]. **ACM** [JS18, JS19, SJ18]. **Acquisition** [FSLN19, LMD14]. **ACT** [THH⁺13]. **ACT-R** [THH⁺13]. **ACT-R/E** [THH⁺13]. **active** [FSP15]. **Activities** [MNM18]. **activity** [CBO⁺16, JBF⁺14]. **acts** [BWS17]. **Adapt** [SHSK20, MM16]. **Adapting** [CBK⁺18]. **adaptive** [HLWV14]. **Adults** [BFW⁺20, JL19, MN13]. **advances** [Goo13]. **affective** [LMD14]. **Age** [CCL⁺19]. **agency** [JL16, SDFSM17]. **Aging** [LR18]. **AI** [Vel18]. **Aid** [MNM18]. **aided** [Tan15]. **Aids** [JL19]. **air** [DLDS⁺15]. **Algorithm**

[HHHA19, KF18]. **analog** [PSB⁺16]. **Analysis** [ASJD19, CT12]. **Android** [Har16, KTTO13]. **animal** [PSB⁺16]. **Animation** [STH19]. **Anthropomorphic** [SS18]. **anthropomorphism** [YZL⁺16]. **appearance** [MHI16]. **Application** [ZFS⁺20, DSPM15]. **applications** [MAC15]. **approach** [Aug14, BRSTV17, BFL⁺17, DSMS17]. **architecture** [THH⁺13]. **aren't** [WM16]. **Argumentation** [SA15]. **Argumentation-based** [SA15]. **arousing** [LJR17]. **Artificial** [HCR18]. **Asimo** [JL16]. **aspects** [You17]. **assessing** [GCMC15]. **Assessment** [HHHA19, ME20]. **assist** [MBK⁺12]. **assistance**

[ITI15, NWS15, SD15]. **assisted** [ZCG⁺20, Ran20]. **Assistive** [JA20, LR18, MNM18, FM13, HLWV14, MN13, SDFSM17, TOW⁺13]. **Attention** [SSK⁺19, RFLM13]. **Attitude** [CCL⁺19, WML15]. **attitude-aware** [WML15]. **Attitudes** [TOW⁺13]. **attributing** [JL16]. **Autism** [JBJ⁺20, KPSS12, SDFSM17]. **automation** [Asa16]. **autonomous** [RFLM13, WM16]. **Autonomy** [JA20, ZZKC19, BFR14, MBK⁺12]. **Average** [RC15]. **Average-position** [RC15]. **avoidance** [ITI15]. **Aware** [CNS⁺20, WML15]. **awareness** [PCB⁺17, PJ17].

Balancing [Mat18]. **based** [BWS17, BTLY15, DLG⁺19, DKI19, FSM12, HBAZ15, MHI16, NWS15, SA15, WS13]. **bases** [DSPM15]. **Behavior** [DKI19, KLE19, ORPW19, HM13, MM16]. **Behavioral** [LZ17]. **Behaviors** [MNM18]. **behaviour** [DSMS17]. **Bender** [dSCV⁺13]. **Better** [FS17, Sch14]. **between** [NWS15, SDFSM17]. **Beyond** [KLE19]. **Bias** [HB18, DSMS17]. **Blossom** [SH19]. **Body** [SS18, LJR17]. **bonds** [BBR⁺13]. **Brain** [ME20]. **Brave** [Bro18]. **break** [SRK14]. **Bridging** [ASJD19, KPSS12]. **Brief** [Dau18]. **building** [BBR⁺13]. **BUSA** [BFL⁺17].

Can [SHSK20]. **capabilities** [dSCV⁺13]. **capable** [MBK⁺12]. **Capacities** [vSPKB20]. **care** [MN13, TM12]. **care-receiving** [TM12]. **categories** [Wag15]. **centered** [MBK⁺12, WML15]. **centric** [KA13, KTTO13]. **character** [Sch14]. **characterizing** [Mil13]. **Charismatic** [FNJB20]. **Chief** [SJ18]. **Child** [vSPKB20, BBR⁺13, CBO⁺16]. **Children** [JBJ⁺20, SHSK20, TM12, FSM12, SDFSM17]. **Clarifying** [DTT⁺13].

Classification [BSC18, HS15]. **classroom** [TM12]. **Clinicians** [JL19]. **Closed** [BA18]. **Closed-Loop** [BA18]. **coach** [FM13]. **Coactive** [JBF⁺14]. **CoBot** [Vel18]. **Cognitive** [DSPM15, HMGC13, LHP⁺13, THH⁺13]. **Collaboration** [CNS⁺20, NKFS18]. **Collaborative** [HHHA19, GCMC15]. **Collision** [BA18, ITI15]. **Collision-Free** [BA18]. **Commands** [SOCAG⁺19, DTT⁺13]. **Communicating** [LCM⁺19]. **Communication** [CCT⁺18, NKFS18, MF15, WBS15]. **comparative** [ZCW⁺16]. **comparing** [BTLY15]. **computational** [FSM12]. **Computing** [MWJO19]. **concept** [MBK⁺12, WM16]. **concerns** [WM16]. **conditions** [PJ17]. **conducting** [TKC14]. **configuration** [WEG⁺13]. **conflicts** [MPCV13]. **connectivity** [PCB⁺17]. **Consent** [SAS19]. **considering** [You17]. **constraints** [Tan15]. **contact** [LJR17]. **continue** [GCSY16]. **Control** [ZFS⁺20, ZZKC19, CT12, DLDS⁺15, GCMC15, Mil13, MAC15, NWS15, SA15, SD15]. **controller** [WML15]. **controllers** [SD15]. **Controlling** [CT13]. **Cooperation** [ME20, MF15, RC15]. **cooperative** [NWS15]. **coordination** [RC15]. **Correct** [LO20]. **course** [You17]. **Covert** [WBS15]. **creating** [Wag15]. **Creative** [Bro18]. **creatures** [OP14]. **Crowdsourcing** [BDO⁺13, TKC14]. **Curiosity** [CCL⁺19, DLG⁺19]. **Curiosity-based** [DLG⁺19]. **customizable** [DSL13].

Daily [MNM18]. **dangerous** [Har16]. **Data** [DKI19, GCSY16]. **Decision** [CNS⁺20]. **demonstration** [SD15]. **Design** [CBK⁺18, MPCV13, Aug14, DSPM15, FLA⁺13, HF14, JBF⁺14, MBK⁺12, PSB⁺16, RFLM13, WML15]. **Designing** [HJ14, HLWV14, KLE19, SRK14, JBF⁺14, WS13]. **determinism** [HLWV14]. **Development**

[LMD14, PB18]. **Diagnostic** [HHHA19]. **dialog** [DTT⁺13]. **dialogic** [MBLD17]. **dialogue** [SA15]. **Dialogues** [SSK⁺19]. **Did** [DLG⁺19]. **Difference** [CCL⁺19]. **Different** [ZZKC19]. **Dig** [BFL⁺17]. **Dimensions** [Oka18]. **direct** [GCMC15]. **dishonest** [Har16]. **Disorder** [JBJ⁺20]. **dissonance** [LHP⁺13]. **Distance** [FSM12]. **Distance-based** [FSM12]. **distributed** [RC15]. **Diverse** [SJ19b, MBLD17]. **Do** [JL19]. **does** [JL16]. **Dominance** [LCM⁺19]. **don't** [Asa16]. **drama** [SCG17]. **driver** [NWS15]. **Drone** [ZZKC19]. **drones** [WM16]. **during** [MPCV13, MU15]. **dynamic** [MBK⁺12]. **dynamic-autonomy** [MBK⁺12]. **dynamics** [CT13].

Ease [CCL⁺19]. **Editorial** [AJS19, JS17, JS19, SJ19a, SJ19b]. **Editors** [SJ18]. **Editors-in-Chief** [SJ18]. **Education** [SBB17, MBLD17, ZCV⁺17]. **EEG** [MHI16]. **EEG-based** [MHI16]. **Effect** [KF18, LRS18]. **Effects** [BSC18, vSPKB20, MHI16, Sch14, YZL⁺16]. **Efficacy** [PB18]. **elderly** [FM13, MBK⁺12]. **embodied** [THH⁺13]. **emergency** [ITI15]. **Empathic** [AOSM⁺19, OP14]. **Enabling** [BWS17, CXJS13, DSPM15, GSF⁺13, HM13]. **endpoint** [MU15]. **Engage** [SHSK20, CBO⁺16]. **engagement** [RFLM13]. **Engaging** [SOCAG⁺19]. **engineering** [Sch14]. **Enhancement** [ZFS⁺20]. **Enhancements** [FSP15]. **enhancing** [Tan15]. **environment** [BDO⁺13, WS13]. **environment-based** [WS13]. **evaluating** [BTLY15]. **Evaluation** [VK19, ZFS⁺20, BDO⁺13, RFLM13, SRK14]. **Event** [Gär19]. **evocative** [LZ17]. **Exceptions** [SAS19]. **exchange** [HS15]. **exchanges** [PJ17]. **Execution** [BA18]. **exercise** [FM13]. **Exoskeleton** [JL19]. **Experience** [KF18]. **Experiences** [JBJ⁺20]. **experimental** [KSNL13]. **experiments** [TM12]. **Explain** [SHSK20].

Explaining [WDR⁺20]. **exploration** [GCSY16]. **Exploring** [SAS19]. **exposing** [You17]. **Expressive** [SOCAG⁺19, VK19]. **eye** [AS17].

Facilitate [JBJ⁺20]. **Facilitating** [CCT⁺18, FSM12]. **facility** [MN13]. **Fascinating** [Vel18]. **Feedback** [CCT⁺18, BTLY15]. **feel** [JL16]. **Fiction** [MWJO19]. **Field** [AOSM⁺19, BFW⁺20, TM12, TOW⁺13]. **floor** [CT13]. **foraging** [KSNL13]. **force** [Asa16, HS15, RFL⁺15]. **forestry** [WS13]. **Formation** [vSPKB20]. **fostering** [PSB⁺16]. **Foundation** [SJ19b]. **Framework** [ASJD19, JBJ⁺20, BFR14, TKC14]. **Frameworks** [Mil13]. **Free** [BA18, ZCW⁺16]. **Functional** [CS13]. **Future** [Dau18, SJ19b, PSB⁺16, WS13].

games [SA15]. **gap** [KPSS12]. **gaze** [AS17]. **GEDIS** [ZFS⁺20]. **GEDIS-UAV** [ZFS⁺20]. **General** [CBK⁺18, dSCV⁺13]. **General-Purpose** [CBK⁺18, dSCV⁺13]. **Generate** [Gär19]. **Generation** [VK19, Tan15]. **Gesture** [CCT⁺18, KTTO13]. **gesture-centric** [KTTO13]. **gestures** [MPCV13, ZCW⁺16]. **Global** [BA18]. **globe** [GE13]. **goals** [HM13]. **graduate** [You17]. **ground** [BTLY15, WML15]. **ground-based** [BTLY15]. **Group** [AOSM⁺19]. **Guided** [FGT18]. **guidelines** [Rie12].

Hacking [HB18]. **hand** [Tan15, ZCW⁺16]. **Handcrafted** [SH19]. **handovers** [SLD⁺13]. **handrest** [FSP15]. **Hands** [Asa16]. **Happy** [Bro18]. **Haptic** [CCT⁺18, NWS15, Oka18, SFEK15, BTLY15, ITI15, RC15, SD15]. **haptics** [MF15]. **helicopter** [DSPM15]. **hesitation** [MPCV13]. **historical** [OP14]. **home** [MBK⁺12]. **homes** [TOW⁺13]. **Households** [BFW⁺20]. **HRI**

[BFL⁺17, PB18, AJS19, Asa16, ASJD19, Bro18, GE13, Goo13, KB13, KPSS12, KA13, MF15, Mat18, MBLD17, Rie12, RFLM13, SBB17, SJ19b, SAS19, You17, ZCV⁺17]. **Human** [BSC18, CCT⁺18, CNS⁺20, DC16, Dau18, DKI19, FGT18, HCR18, HHHA19, HF14, HB18, JA20, JH18, KG18, KSNL13, KF18, LO20, MF15, ME20, NKFS18, ORPW19, Oka18, PSB⁺16, PB18, SJ18, STH19, SSK⁺19, Vel18, vSPKB20, AS17, BFR14, BFL⁺17, BDO⁺13, BTLY15, BGJK16, CS13, CXJS13, DTT⁺13, GSF⁺13, GCMC15, HBAZ15, HMGC13, HS15, KTTO13, LMD14, LHP⁺13, MHI16, MPTCV13, MU15, PJ17, dSCV⁺13, SA15, SLD⁺13, TGS12, Tan15, TKC14, THH⁺13, Wag15, WBS15, vdBBD⁺16]. **Human-animal** [PSB⁺16]. **Human-Guided** [FGT18]. **Human-Human** [ORPW19]. **Human-Mobile** [CCT⁺18]. **Humane** [SS18]. **Humanoid** [SS18, DSMS17, FLA⁺13, LJR17].

Ideas [FS17]. **If** [JL16]. **Impact** [ZZKC19, DSMS17, JS17, MPCV13]. **implications** [JL16, WBS15]. **Implicit** [CCL⁺19]. **importance** [You17]. **improve** [MM16, vdBBD⁺16]. **improved** [PCB⁺17]. **Improving** [HS15]. **inaugural** [TGS12]. **inclusion** [JS17]. **Increasingly** [Vel18]. **indirect** [BWS17]. **individuals** [KPSS12]. **influencing** [PSB⁺16]. **information** [DTT⁺13, PJ17]. **information-theoretic** [DTT⁺13]. **infrared** [CS13]. **initiative** [DLDS⁺15]. **initiatives** [ZCV⁺17]. **Intelligence** [HCR18]. **intelligent** [DSL13, TOW⁺13]. **Intent** [JA20]. **interacting** [MKH14]. **Interaction** [Dau18, FDN20, HCR18, JH18, KLE19, KG18, KF18, ORPW19, Oka18, PB18, STH19, Vel18, AS17, BFR14, BBR⁺13, BFL⁺17, BDO⁺13, BTLY15, BGJK16, CS13, CXJS13, CBO⁺16, FSM12, FLA⁺13, GSF⁺13, HM13, KSNL13,

KTTO13, LMD14, LHP⁺13, MBK⁺12, MU15, OP14, RFL⁺15, dSCV⁺13, TKC14, THH⁺13, Wag15, WS13, WBS15, vdBBD⁺16, DC16, HF14, MF15, SJ18]. **Interactions** [LO20, ORPW19, BWS17, CT12, HMGC13, SFEK15, SDFSM17]. **Interactive** [SCG17, YZL⁺16]. **interdependence** [JBF⁺14]. **interdisciplinary** [TGS12]. **Interface** [ZFS⁺20, PCB⁺17, RFL⁺15]. **interfaces** [DSL13]. **Interference** [FDN20]. **intergroup** [DSMS17]. **interrupt** [RFLM13]. **Interruptibility** [BSC18]. **intersection** [TGS12]. **Introduction** [DC16, GE13, Goo13, HCR18, HF14, JS19, KB13, MF15, MAC15, SBB17, TGS12, JS17]. **invariants** [BGJK16]. **investigating** [WM16]. **invitational** [Goo13]. **Issue** [HCR18, JS19, SBB17, DC16, GE13, Goo13, HF14, KB13, MF15, MAC15, TGS12]. **JHRI** [Goo13, JS17]. **joint** [JBF⁺14]. **Journal** [DC16, HF14, MF15].

Kill [DLG⁺19]. **kinesthetic** [WEG⁺13]. **knowledge** [CXJS13].

laboratory [TOW⁺13]. **Lack** [vSPKB20]. **Language** [Ran20, SHSK20]. **law** [DC16]. **Learned** [BA18]. **Learning** [AOSM⁺19, AJS19, CNS⁺20, DLG⁺19, DKI19, FSLN19, KF18, LO20, MNM18, ORPW19, Ran20, SHSK20, SD15, WDR⁺20, BFL⁺17, TM12]. **legal** [JL16]. **Levels** [ZZKC19, BFR14]. **likeness** [MHI16]. **Linguistic** [FSLN19]. **Literature** [MWJO19, STH19]. **Living** [Aug14, MNM18]. **Locomotion** [LCM⁺19]. **long** [CBO⁺16, MN13]. **long-term** [CBO⁺16, MN13]. **Longer** [LRS18]. **Longer-Term** [LRS18]. **looking** [WM16]. **Loop** [BA18].

machines [LZ17, WS13]. **magic** [Sch14]. **makes** [Sch14]. **Making** [CNS⁺20, KPSS12].

management [SRK14, TKC14]. **manipulability** [SFEK15]. **manipulation** [MBK⁺12]. **manipulation-capable** [MBK⁺12]. **Mapping** [FGT18]. **Matters** [FNJB20]. **may** [RFLM13]. **Meal** [MN13]. **Meal-time** [MN13]. **measure** [LHP⁺13, MHI16]. **Measures** [FDN20]. **mechanical** [LJR17, OP14]. **Mechanisms** [FSLN19]. **Melody** [FNJB20]. **Memory** [DKI19]. **Mental** [HBAZ15]. **metamorphosis** [OP14]. **method** [HLWV14]. **methodology** [Tan15]. **Methods** [BTLY15, VK19, BDO⁺13, WS13]. **Mind** [SS18, HJ14]. **Mixed** [DLDS⁺15]. **Mixed-initiative** [DLDS⁺15]. **Mobile** [BFW⁺20, CCT⁺18, Vel18, BTLY15, RFL⁺15]. **Mobility** [JL19, SD15]. **Model** [CNS⁺20, DKI19, CT13, MKH14, MU15, Tan15]. **Modeling** [SSK⁺19]. **models** [FSM12]. **Modified** [ZFS⁺20]. **Monitoring** [ME20]. **Morphology** [KLE19]. **Motion** [BA18, SOCAP⁺19, MHI16]. **Motions** [VK19]. **Motor** [FDN20]. **movement** [HJ14, Tan15]. **Movie** [Sch14]. **mu** [MHI16]. **multi** [CBO⁺16, KTTO13, RC15, SFEK15]. **multi-party** [CBO⁺16]. **multi-party** [KTTO13]. **multi-robot** [SFEK15]. **multi-user** [RC15]. **multidisciplinary** [BFL⁺17]. **Multilevel** [ASJD19]. **Multimodal** [BBR⁺13, KLE19, ZCG⁺20, CT12, LMD14]. **Multiparty** [SSK⁺19].

Natural [FLA⁺13]. **near** [CS13]. **near-infrared** [CS13]. **need** [GCSY16]. **needs** [MM16]. **Negation** [FSLN19]. **Negative** [CCL⁺19]. **nets** [CT12]. **network** [DKI19, GSF⁺13, PCB⁺17]. **networked** [RC15]. **Neural** [DKI19]. **Neural-network-based** [DKI19]. **No** [FSLN19]. **non** [DLDS⁺15, SCG17]. **non-pilots** [DLDS⁺15]. **non-technical** [SCG17]. **Nonanthropomorphic** [LCM⁺19]. **Norm** [SAS19].

obedience [GCSY16]. **Object** [FGT18, HS15]. **Objective** [ME20]. **objects** [LZ17]. **Older** [BFW⁺20, JL19, MN13]. **online** [HS15]. **Ontology** [ORPW19]. **Open** [SSK⁺19, SH19, CXJS13]. **Open-Source** [SH19]. **Open-World** [SSK⁺19]. **operation** [NWS15]. **Operator** [ZZKC19, MU15]. **Opportunity** [Vel18]. **Our** [SJ19b]. **overlap** [Sch14]. **overview** [OP14]. **Oz** [Rie12].

Paediatric [CBK⁺18]. **paired** [SD15]. **paradigm** [KA13]. **parametrized** [CT13]. **parts** [LJR17]. **party** [KTTO13]. **Past** [Dau18]. **pedestrian** [ITI15]. **peer** [HBAZ15]. **peer-based** [HBAZ15]. **people** [BRSTV17, MBK⁺12, MM16, Wag15]. **Perceived** [CCL⁺19, MHI16, YZL⁺16]. **Perception** [vSPKB20]. **perceptions** [WBS15]. **performance** [HBAZ15, vdBBD⁺16]. **Personalization** [LRS18]. **Personalizing** [MNM18]. **perspective** [KA13, PJ17]. **perspectives** [GE13]. **Petri** [CT12]. **Physical** [LO20, ME20, GCMC15, MU15, PCB⁺17]. **Physiological** [ZCG⁺20]. **physiologically** [LJR17]. **pilots** [DLDS⁺15]. **planar** [FSP15]. **Planning** [BA18, CNS⁺20, NKFS18]. **platform** [LMD14]. **Please** [GCSY16]. **police** [Asa16]. **Policies** [ORPW19]. **policy** [DC16]. **poor** [vdBBD⁺16]. **position** [RC15]. **Practice** [Mat18]. **Prediction** [ZCG⁺20, MU15]. **Preliminary** [JBJ⁺20, RFLM13]. **Presence** [MWJO19]. **privacy** [WM16]. **Private** [BFW⁺20]. **Probabilistic** [JA20]. **problem** [BFL⁺17]. **Process** [JS18]. **Profit** [FNJB20]. **progress** [MBLD17]. **Prohibition** [FSLN19]. **projects** [GE13]. **Promote** [LR18, MBLD17, TM12]. **prototype** [SRK14]. **proxemic** [MM16]. **Psychological** [vSPKB20]. **public** [BDO⁺13, GSF⁺13]. **Purpose** [CBK⁺18, dSCV⁺13]. **push** [GCMC15].

Quality [FDN20].

R/E [THH⁺13]. **R2D2** [KLE19]. **RALL** [Ran20]. **reactions** [LHP⁺13]. **Reactive** [BA18]. **Real** [LO20, BFL⁺17]. **Real-Time** [LO20]. **real-world** [BFL⁺17]. **Reasoning** [WDR⁺20]. **receive** [DSPM15]. **receiving** [TM12]. **Recognition** [JA20]. **reconnaissance** [WML15]. **reduce** [HLWV14]. **redundant** [WEG⁺13]. **Reflecting** [MWJO19]. **reformulation** [MBLD17]. **Reframing** [LR18, MBLD17]. **regulating** [Har16]. **regulation** [CT13]. **Rehabilitation** [CBK⁺18, Tan15]. **Reinforcement** [KF18]. **Rejective** [FSLN19]. **related** [Tan15]. **Relationship** [vSPKB20]. **relationships** [Mil13]. **Relevance** [Mat18]. **remote** [DSPM15, MBK⁺12]. **repertoire** [HM13]. **reporting** [Rie12]. **Representation** [AJS19, RFL⁺15]. **Representations** [Gär19]. **research** [KPSS12, YZL⁺16]. **resource** [MPCV13]. **Results** [BFW⁺20, TOW⁺13]. **resupply** [DSPM15]. **Review** [JS18, STH19, AS17, Rie12, ZCV⁺17]. **Reviewer** [FS17]. **Reviewing** [FS17]. **rhythm** [MHI16]. **rise** [LZ17]. **roadable** [DLDS⁺15]. **Robot** [AOSM⁺19, BFW⁺20, BSC18, CBK⁺18, CCT⁺18, CNS⁺20, DC16, Dau18, DLG⁺19, DKI19, Gär19, HCR18, HHA19, HF14, JH18, KLE19, KG18, LRS18, LCM⁺19, LO20, MF15, ME20, MNM18, NKFS18, Oka18, PB18, SJ18, STH19, SH19, Tan15, Vel18, VK19, WDR⁺20, ZCG⁺20, vSPKB20, AS17, BRSTV17, BFR14, BBR⁺13, BFL⁺17, BDO⁺13, BTLY15, CS13, CXJS13, CBO⁺16, DTT⁺13, DSMS17, FM13, FSM12, FLA⁺13, GSF⁺13, GCMC15, HBAZ15, HMGC13, HS15, HM13, KA13, KTTO13, LMD14, LHP⁺13, LJR17, MHI16, MN13, MM16, MPCV13, MKH14, MU15, PSB⁺16, PJ17, RFL⁺15, dSCV⁺13, SRK14, Sch14, SFEK15,

SA15, SLD⁺13, TM12, TKC14, THH⁺13, Wag15, WBS15, YZL⁺16, vdBBD⁺16, Ran20]. **Robot-AI** [Vel18]. **Robot-aided** [Tan15]. **Robot-assisted** [ZCG⁺20, Ran20]. **Robot-Interaction** [PB18]. **Robot-specific** [KLE19]. **robot-to-human** [PJ17]. **Robotic** [JBJ⁺20, SOCAG⁺19, OP14]. **Robotics** [HB18, JA20, YZL⁺16, ZCV⁺17]. **Robots** [CCL⁺19, FNJB20, FSLN19, JH18, LR18, MM16, MWJO19, SS18, SHSK20, Vel18, Wag15, Aug14, BWS17, BTLY15, GCSY16, Har16, HJ14, HM13, HLWV14, MBK⁺12, SRK14, SCG17, Sch14, SDFSM17, TOW⁺13, WML15, WEG⁺13]. **Robots-from** [SS18]. **Robust** [JH18]. **Role** [SAS19, HLWV14]. **roles** [HLWV14]. **Roomba** [JL16].

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[HCR18, SBB17, DC16, GE13, Goo13, HF14, KB13, MF15, MAC15, Sch14, TGS12].
specific [KLE19]. **spectroscopy** [CS13].
Spectrum [JBJ+20]. **speculative** [Aug14].
Speech [FNJB20, BWS17]. **Spring** [SJ19b].
status [NWS15]. **steering** [NWS15].
stereotype [Wag15]. **stereotypes**
[HLWV14]. **stiffness** [MU15]. **Strategies**
[ZZKC19]. **students** [ZCV+17]. **Studies**
[STH19, KB13, LMD14, Rie12, TKC14,
TOW+13]. **Study**
[AOSM+19, BSC18, JBJ+20, SHSK20,
KSNL13, WEG+13, ZCW+16]. **subjects**
[SCG17]. **Successful** [LR18]. **Supervisory**
[HHHA19, Mil13]. **support**
[JBF+14, YZL+16]. **Supporting** [PJ17].
suppression [MHI16]. **Surgery**
[ZCG+20, ZCW+16]. **surroundings**
[PCB+17]. **Survey** [Ran20, VK19].
sustainability [JS17]. **swarm**
[BGJK16, KSNL13]. **Swarms**
[SOCAG+19, KSNL13, SFEK15]. **switching**
[CBO+16]. **System**
[DLG+19, BDO+13, GSF+13, ITI15, KB13,
KTTO13, NWS15, TKC14]. **Systematic**
[STH19, Rie12]. **systems** [SA15, TGS12].

tactile [LJR17]. **taking** [CT12, PJ17].
Talking [WDR+20]. **Tap** [GCMC15]. **Task**
[FGT18, BWS17, HBAZ15, Tan15, WEG+13].
task-based [BWS17]. **task-related** [Tan15].
Tasks [BA18, GCMC15]. **teach** [TM12].
teaching [SCG17, WEG+13]. **Teams**
[HHHA19, HBAZ15, PSB+16]. **technical**
[Goo13, SCG17]. **Technique** [ZFS+20].
Techniques [STH19]. **technological**
[HLWV14]. **technologists** [You17].
Technology [JL19, JL16, You17].
Teleoperation
[CCT+18, DSL13, PCB+17, RFL+15, WS13].
telepresence [HMGC13]. **telerobotic**
[ZCW+16]. **Term** [LRS18, CBO+16, MN13].
testing [LMD14]. **their** [MM16, TM12].
theoretic [DTT+13]. **Theories** [JH18].

Theory [Mat18]. **These** [WM16]. **Think**
[JL19]. **thinking** [MBLD17]. **thinks** [JL16].
Thoughts [Dau18]. **threat** [YZL+16].
Three [FS17]. **THRI** [JS18, JS19]. **Time**
[ASJD19, JH18, LO20, MN13]. **timed**
[CT12]. **Timing** [CT12]. **together**
[MKH14]. **too** [MM16]. **Touching** [LJR17].
Traditional [JL19]. **Training** [ZZKC19].
Trajectory [LO20, Tan15]. **Transactions**
[SJ18]. **Transfer** [FGT18]. **Transparency**
[vSPKB20]. **Trials** [BFW+20, TOW+13].
Trust [CNS+20, DSMS17, PSB+16].
Trust-Aware [CNS+20]. **trustworthy**
[ITI15]. **tu** [Har16]. **turn** [CT12].
turn-taking [CT12]. **Tutoring** [LRS18].
Two
[BGJK16, BRSTV17, KSNL13, ZCV+17].
types [KSNL13].

UAV [ZFS+20]. **UGV** [PCB+17].
Unconventional [ZCV+17]. **understand**
[BWS17]. **Understanding**
[JS18, SDFSM17, MM16]. **uninhabited**
[Mil13]. **unmanned** [DSPM15]. **Use**
[CCL+19, Asa16, BTLY15]. **useful**
[KPSS12]. **User** [MBK+12, STH19, WML15,
RC15, RFL+15, WEG+13]. **User-centered**
[MBK+12, WML15]. **users** [CBO+16].
Using
[FNJB20, Gär19, LCM+19, ME20, CT12,
CBO+16, SFEK15, Tan15, Wag15, ZCW+16].

Validation [PB18]. **value** [GCMC15].
vehicle [DLDS+15]. **vehicles** [Mil13].
Verbal [NKFS18]. **via** [CCT+18]. **videos**
[WM16]. **Virtual** [WS13]. **Visual**
[RFL+15, SSK+19]. **visuospatial** [PJ17].
vocabulary [TM12]. **Volume** [JS19].

Walking [MKH14]. **Warning** [vdBBD+16].
Welcome [SJ18]. **We're** [WDR+20]. **Wild**
[JH18, SRK14]. **Wizard** [Rie12]. **work**
[TGS12]. **Workload**
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Wong:2016:AAD

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Zhou:2016:CST

Zhou:2020:MPS

Zhang:2020:EAU

Zenk:2017:USR

Zhou:2019:IDL

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