Title word cross-reference

- Coverage [PPCE22]. -persistent [BDMP12]. -values [ZLHC21].


Adaptao [DCL+12]. Adaptation [AMG18, BVPD17, Buc19, CMGS16, CLSS+13, EYCM16, FMVC14, GGPTRC16, HBMA21, KKK+16, MCGS18, RMKM17, WQQV22, ZNU21, DCL+12, KGI12, PSB+12, RTH19, ZP12]. Adaptations [PBW+20]. adaptive [HKR08].


3PC [HSM+12].

802.15.4 [BRDA16].

Agent [AA16, ADV16, BRII21, CLSS+13, CW14, EGSM21, GR08, LCQB21, LV07, MDC17, PBP17, WCW+17, FRL09, GCC06, Hkr08, KG12, MLS22, Pos07, WHH+10b, WHH10a, ZLHC21].

Agent-based [EGSM21, GCC06].

AgentLink [POPM07]. Agents [BEE+20, Buc19, DBDF19, FCD+18, RH16, SB19, SZY+20, JI07, MIRG06, PPSM07].


Airborne [BUL+18]. Algorithm [BMPB23, BRDA16, RGP+15, SBMM17, APA12, MZH13, SLJS08].

Algorithmic [VW18]. Algorithms [BSS+14, CFGM16, DP16, FMSA11, Gab11, SCC17, BN12, DKMD11, FMS08, KG10, PB13, WDT11].

Allocation [ASS+15, AH21, BR1I21, JZL15, KPO19, ZCS12]. Ambient [CLRC21, AGLV10, DHC10, Her10, LV10].

Analytic [BCF18, AKLG22, GPT+16, KTK+16, SG13, SBMM17, Lit07].

Analytic [LFA9]. Analyzing [CMGS16, WN12a]. Android [RMM19].

Anomaly [LJIZ21, ZSO9]. Anonymity [BRI1]. Anonymous [DK12, MT09]. Ant [SLJS08, LDD06, PB13]. Ant-based [SLJS08]. Anticipatory [ZHSP20].

Anycast [CW11]. Application [GCC06, LR12, PSB+12]. Applications

[BDLM11, FBL18, GB14, HBDD14].

LCT+18, LDC+18, MS15, MVV14, SRRB13, ZSLG16, AGLV10, CSLZ10, LS09, USC+08].

Applying [GWQ21]. Approach [CMRZ15, CLW+14, DLPT14, EK21, Gab11, JAJ+18, LC21, MVV14, Men16, PPCE22, SWM19, SZB19, VMG14, VGR+15, WVT+17, AVG09, GPT13, GYS10, GR10, LV07, PSB+12, PSFC12, XVH11].


Architectures [GGV20]. Area [HBDD14].

Argumentation [SDOP20].

Argumentation-Based [SDOP20]. Array [PSPR15]. Arrays [HMF+15]. Articles [FMVC14].

Artificial [CHC16]. Assembly [FP17, GR10, TGT+06]. Assignment [RW20]. association [DHC10]. Assured [ZNU21].


Augmented [LJIZ16]. Authentication [BCC+23]. Auto [DRQ14, LDC+18].

Auto-Proﬁling [LDC+18]. AutoHome [BDLM11]. Automated [FE12, KIWO6, MLLS+15].

Automatic [SC19, CLH+12, DCL+12]. automatically [YTWO8].

Automaton [MG11].

Autonomic [AOK11, BBC+11, BDLM11, DXP14, DLPT14, DC12, IA18, LZ13, LF19, MHP+12, TWS20, AVCO9, DDF+06, KMS08, LS09, Lit07, XVY11].

Autonomous [BCC+17, BWW+17, DAHS21, FCD+18, Gab11, MPBM+10, SMHP15, WN12a, WN12b]. AutoPlacer [PERR15].

Availability [CLRC21, RDKB15, LLL12]. Aware [CMGS16, FCD+18, MCGR18, SAK20, DZJ+21, DBA+21, FS09, GSD08, PBW+20, RTH19].

Awareness [LV07, ESBT19, PRJ11].

Axiomatization [PSA12].

backend [SA06]. Balancing

Construction [BWO17, War19].
Consumption [FCD+18]. Containerized [SMK21]. Containment [CLW+14].
Continuous-Time [CW14]. Control [ALKG22, APSM18, ARS17, BDMP12, DAHS21, EK1, FMA+17, FDMD15, HWH+17, KLWS16, KKK+18a, KKK+18b, LZ13, LF19, LDL16, MVV14, RMKM17, SWM19, SKA20, VMG14, WUK+18, XLXZ14, GYS08, KM08, LR12, LND12, WCD+09]. Control-A [EK21]. Control-based [BDMP12].
Cooperative [ASS+15, HLM15, MVV14, TMC+11].
Data [CMP13, DRPQ14, LVP15, LF19, LCT+18, M16, MCB20, PRRR15, RDKB15, dASH16, ZSA09].
Death [KD16]. Decentralised [ONC17, PPCE22]. Decentralized [AOK11, ARS17, KGJ12, KB13, LND12, PPA18, RDKB15, SKA20, QPGS12].
Decision [AA16, KKK+18b, MHP+12, MCGS18, SS12].
Deployment [SZB19, WDTSS11]. Description [Dua11]. Design [ARS17, BCD+06, BBDB15, CHC16, CW11, CMP13, FE12, GDA10, DW15, QPGS12, PPSM07].
Detection [CLW+14, IJDZ16, ONC17, SQX+07, YTW08, ZS09]. detectors [ZS09].
Develop [BSK20]. Device [BVPD17, DY08]. Devices [BSK20, Das12].
DevOps [FBL18]. DIFC [SKA20].
different [APA12]. differential [APA12, CEA08]. dimensional [WCD+09].
Disaster [SZB19]. Discovery [Bak11, CW11, Dua11, FGB11, DHC10].
Discrete [SMHP15]. Dispersion [Bec15].
Distributed [BMPB23, BMS11, DGL+11, FB15, FSW+10, GMMB15, HMF+15, KLWS16, LVP15, LEC+15, MM17, MVV14,
Men16, PRRR15, RPG+15, RTN+17, SHRB13, SMHP15, VWT+17, War19, BCD+06, Dat08, Dat09, HSL+07, LMSM12, LR12, RYC+07, SLJS10, WMA12, ZCS12. Distribution [BVPD17, GB14].

Distributive [PBM14]. Disturbances [GMNB15]. Diverse [AH21, LDL16].


e-Sampling [BWW+17]. Economic [FBL18, PSA12]. Economies [PPA18].

Ecosystems [CMRZ15]. Edge [LHAES23]. Editorial [LV10, Nus18, PZ11, PZ13, PZ18, VP09, WBSI10]. Effective [VA11, WUK+18, WGQV22]. Efficiency [CGZ15, Das12]. Efficient [CFG16, DAHS21, GGP12, HSC+18, HLLL21, MCGS18, WGQV22, WXZ10].

Eigenspace [SQX+07]. Elastic [DRPQ14, Men16]. Elasticity [GS18].


Experiments [PSA12]. Explanation [ALGK22]. Explicit [WUK+18]. Exploiting [AHM09, HBDD14].

Expression [KIW06]. Extended [CPS17, PH15, VDK16]. Extending [PPSM07]. Extracting [VHK+17].

Extraction [SC19].


inhibitory-coupled [KB12]. Initial [KB15].
Innovative [SZB19]. insights [XLX12].
Innovative [GMM12, MR11, VCMZ11, XZL11, FMS08, GR10, KGJ08, LDD06, LS09].
Instances [PRB16]. Institutions [PSA12].
Integrals [KD16]. Integrating [WCW+17].
Intelligence [CLRC21, AGLV10, DHC10, Her10, LV10].
Intelligent [CW14, DHC10]. Intensity [CLRC21, AGLV10, DHC10, Her10, LV10].
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Mechanisms
[KKK+18b, TVKB16, DRVF14, CSLZ10].

Media [SR16].

Memory
[DRPQ14, AL09, SDY09]. memory-less
[SDY09]. message [BW09].

message-driven [BW09]. Method
[BBDB15, FE12, KKK+18a, LDC+18, ZHSP20, CSLZ10, Lit07, PSFC12].

Methodologies [PSFC12]. Methods
[XZL11, BCC+12, FSW+10]. Metric
[MG11]. Microgrids [FDM15].

Microservice [HBMA21]. Middleware
[FBG11, FRL09, WHH+10b, ZS09].

Migrations [LCT+18, WVT+17].

MiniMax [CEA08]. minority [AL09].

Mission [ZNU21]. Mitigating [BSS+14].

Mix [LWQL16]. Mixing [Bea15]. Mobile
[BCC+17, CW11, MR11, SZB19, WVT+17, XZL11, DLIP08, FRL09, SDY09].

Mobility
[Buc19]. Mode [JB11]. Model
[APSM18, BSS+14, BBDB15, IA18, LCQB19, LHAES23, PBW+20, VG14, GCC06, WS10, WHH10a, WMA12].

Model-Based [IA18, PBW+20].

Model-Driven [BSS+14, VG14, LHAES23].

Modeling [ALKG22, BBBD15, DBDF19, DBA+21, FCD+18, KD16, LXX+14, MCBP20, SQX+07, VHK+17, WNV12a, ZCVM13, CGPP12, WNV12b]. Modelling
[BCC+23]. Models [BN12, VA11].

Modular [BMPB23]. Modulation
[WUK+18]. Monitoring [BBW+17, CV19, FG15, ZHSP20, BLK+09, HSL+07].

morphogenetic [GJM12]. Motion
[HWH+17]. Multi
[ADV16, AH21, Buc19, CLSS+13, GGPTRC16, GB14, LV07, MDC17, MAL12, PPB17, PPF22, SJ18, WCW+17, ZLHC21, DHCl0, DC12, HAML13, HRR08, MHZ13, Pos07, TGT+06, USC+08, ZS12].

Multi-Agent [ADV16, CLSS+13, LV07, MDC17, PPB17, WCW+17, MAL12, ZLHC21, HRR08, Pos07]. Multi-Agents


multi-objective [HAMR13]. multi-policy
[DC12]. Multi-Robot
[AH21, SJN18, PPF22, TGT+06, ZS12].

multi-society-based [DHIC10].

Multi-Tasking [AH21]. Multi-Tenant
[GGPTRC16]. multi-tier [USC+08].

Multiagent
[HL13, HLM15, JA+18, SQX+07, WS10].

multicast [AVC09, SLJS08, XYYH11].

Multidimensional [GMM12]. Multilateral
[HL1L21]. Multilayered [LV07].

multilevel [JL17]. Multimedia [MM17].

Multiobjective [FDMD15]. Multiplex
[JZL15]. multirate [XYYH11]. Multirobot
[DJ+21, KLWS16, GJM12]. Multiscale
[FDM15]. Multitolerance [CEK14].

mutation [WXZ10]. mute [BW09].

Mutual [RTH19].

Natural
[HWH+17]. nature
[GR10, KGJ08]. nature-inspired
[GR10, KGJ08]. necessary [CY07].

Negative [TK+16]. Negotiation
[CW14, SR16, GR08, PTW07]. Nervous
[DXP14]. Network
[DCL11, FE12, IJDZ16, SQX+07, SZB19, BLK+09, GSD08, LS09, LR12].

Networked
[BWW+17, CEA08]. networking [LPZ09].

Networks
[AGM18, BRI12, CW11, CMP13, FGB11, GMM15, JCL15, KRM16, KKK+16, KKK+18a, LEC+15, LDDL16, LXX+14, M17, Mam11, M1R11, MOP21, MCP+15, RMK17, XLXZ14, AW10, AD09, DK12, FRL09, GLLMN09, HLS+07, LLL12, MPBMP+10, MT09, MS12, PRJJ11, SA12, VSMS13, WCD+09, WNV12a, WNV12b, WNET07, XYYH11, XLX12, ZSA09].

Neural
[LC+13]. Nodes [KRM16]. Non
[MDC17]. Non-Stationary [MDC17].

Norm [MALS22]. Normative [MLsRA+15].
Norms
[ADV16, HSC+18, SDOP20].
Number [dASH16].

objective [HAMR13]. Obstacles [CV19]. omega [BW09]. Online [IJDZ16, MKS21, MLsRA+15, SCC17, QPGS12]. Open [ASS+15, ST13, RYC+07], operators [WXZ10]. Opponents [CW14].

Opportunistic [BUL+18, CMP13, MPC+15]. Optimal [BW09, BR11, BRDA16, HL13, KKK+18a, LND12]. optimistic [Das12]. Optimization [CPZZ20, LDC+18, MHP+12, ZCVL13, DC12, HAMR13, WDT51]. optimizer [WXZ10]. Optimizing [SMK21, GYSD08, LR12]. Options [WV18].


Peer-to-Peer [LXX+14, DHJ08, HSM+12, KGJ08, LMSM12, WNET07]. Percentile [LZ13]. Percentile-Based [LZ13].

Perception [FP17]. Performance [BSS+14, CGJZ15, CMP13, Dua11, GS18, LF19, LDC+18, SMK21, ZCVL13, LIt07, MSA09]. performance-robust [MSA09].

Periods [RB17]. persistent [BDMP12].

Perspective [HWA+20, JAJ+18].

perturbations [GYP12]. Pervasive [Bak11, BDL11, CMRZ15, CD11, Dua11, Gab11, MZ07, SHRB13, VCMZ11, BCC+12, DC12, GPTW13, HSM+12, SF12, ZP12].


Placement [BCC+17, PRRR15, Her10].


Principles [PSA12]. Privacy [SR16].

Proactive [MCMS18, VMG14].

Probabilistic [CV19, GF19]. problem [GCC06]. problem-solving [GCC06].

Process [LCT+18]. Processes [KD16, BW09].

Processing [HEC+16, Men16, PSPR15].

Profiles [VHK+17].

Profiling [DC12].


QoS [AHM09, DBA+21, GSD08]. QoS-aware [DBA+21]. queries [GYP12].


Ranking [WNET07]. Rational [VA11, ZS09]. REACT [PBW+20].

REACT-ION [PBW+20]. Reactive [SA06, WV18, GCC06]. reading [MS12].

Reality [HWH+17]. Reasoning [SDOP20].

Rebalancing [CPZZ20]. Recognition [HMF+15]. reconfigurability [RYC+07].

Reconfigurable [BSK20, PRJ11].


Regulation [CLSS+13]. Reinforcement [BSK20, GF19, HL13, HLM15, KB15, MDC17, MAFS+18, RW20, VGR+15, WCW+17, ZLHC21]. reinforcing [VSM+13]. RelaxDHT [LMSM12].


retrieval [MIRG06]. Reuse [GF19, KGL21].


Rigorously [DW15]. Risk [DZJ+21].

Risk-aware [DZJ+21]. Robot [AH21, BMPB23, BBDB15, KD16, SJN18, SBMM17, SCC17, WV18, War19, GLMN09, JH17, PPCE22, TGT+06, ZCS12].

Robot-based [BMPB23]. robots [DLIP08, LDD06, SDY09].

Robust [CLSS+13, HSC+18, LC21, VSMS13, MSA09].

robustness [KB12]. role [RYC+07, WNV12a]. roles [RYC+07].

Routing [MR11, VGR+15, MZZ013, PRJ11, PB13, SLJS08, ZSA09].

rtual [BCF+08].

rule [GR10]. run [HSL+07]. run-time [HSL+07]. Runtime [CV19, KTK+16, PBW+20, RMM19, RTH19].

SAC [FMVC14]. Safe [DHJ08, GF19].

Safety [ST13, Dat08, Dat09]. Sampling [BW+17, LVP15]. SAPERE [CMRZ15].

SARDE [GEB+21]. SASO [CP17, PH15, VDK16].

Scaleability [DBA+21, GGV20]. Scalable [FBL18, JB11, PRRR15, ZLS22, BLK+09].

Scale [KKK+16, KKK+18a, RGG+15, AD09, MCPB20, WCD+09].

Scaler [DRPQ14]. Scaling [DRPQ14]. ScatterD [WDT11].

SCEL [DLPT14].

Scenarios [AH21].

Scheduling [RB17]. Scientific [RB17, HAMR13].

SDN [MAFS+18].

SEAMS [BE16, Edi14, SI17]. Search [KGL21]. secret [SA12, MOP21]. Section
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Theoretic [Men16, RDKB15, SWM19].
theoretical [AVC09, GYSD08]. Theory [MOP21, YHT16, KM08]. Things [BVPD17]. Three [GB14, WCD+09].
three-dimensional [WCD+09]. Three-Tier [GB14]. Thresholds [XLX12, XLXZ14]. Tier [GB14, USC+08].
Tight [SBMM17]. Time [BRDA16, CW14, HSL∗07, MHZ13].
tolerance [AD09]. tolerant [WCD∗09, XWN09]. Topology [LDL16, MM17, RMKM17, MT09, WCD+09].
Trace [HLLL21]. Trace-based [HLLL21]. Tracking [KLWS16, GCC06]. Tradeoff [RTN∗17]. traffic [FSW∗10]. Train [LC21].
Transactional [DRPQ14, DRPQ14]. transactions [DK12]. transfer [GYSD08].
UAVs [ZHSP20, ZNU21]. Ubiquitous [Bak11, CD11, Dua11, LV07, TMC+11].
Uncertainty [HWA∗20, KGL21, KKK∗18b, SWM19, SMHP15]. Understanding [BCC∗23, JAI∗18]. Underwater [LDL16, MOP21]. unified [WXZ10].
Unifying [WMA12]. Units [LF19].
UNITY [BEK09]. Unknown [CLW∗14, CW14]. unreliable [GLMN09]. upon [ZS09]. Urban [Buc19, HBDD14].
User-Centric [GGPTRC16]. User-Defined [HWH∗17]. users [GSD08]. Using [BSS∗14, BSK20, CMGS16, FP17, KCH14, KD16, MAFS∗18, PRB16, RH16, SMK21, SDY09, YHT16, ZHSP20, Das12, HAMR13, HSL∗07, KIW06, MKS21].
Utility [GGV20, DRVF14]. Utility-Based [DRVF14]. Utility-Driven [GGV20].
Value [AMS∗19, PRRR15, RTN∗17]. values [ZLHC21]. variability [PPSM07]. Variable [dASH16]. variations [KIW06].
vehicle [MPBMP∗10]. Verification [ARS17, CD11, CY07]. Verified [ZLS22].
WA [MS15]. weak [DLIP08]. Web [GYSD08, MS15, PTW07]. Web-Based [MS15]. Wireless [AMG18, LDL16, MM17, RMKM17, SZB19, AHM09, AD09, BLK∗09, FSW∗10, FRL09, HSL∗07, LPZZ09, MPBMP∗10, MIRG06, SA12, WCD∗09].
within [SJN18]. WLANs [AHM09]. Workflow [PRB16, CY07, HAMR13].
Workflows [RB17, SC19, CGPP12]. Workloads [LHAES23]. World [MS11].
Worm [CLW∗14]. Worms [LXX∗14]. writing [MS12]. WSNs [BRDA16].
XtreemOS [SSN∗12].

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